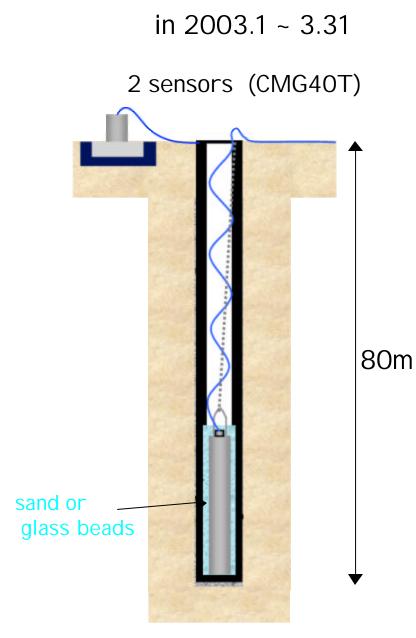
# Preliminary Results of KEK-GM Measurement

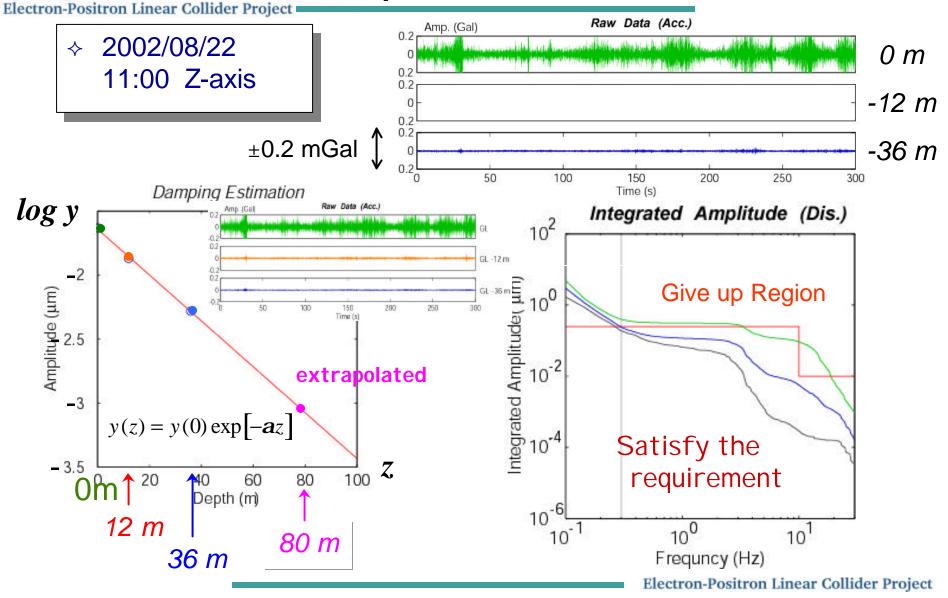
T.Tauchi, K.Fujii, T.Matsuda, H.Yamaoka, N,Uchida, ISG10, SLAC,2003.6.17

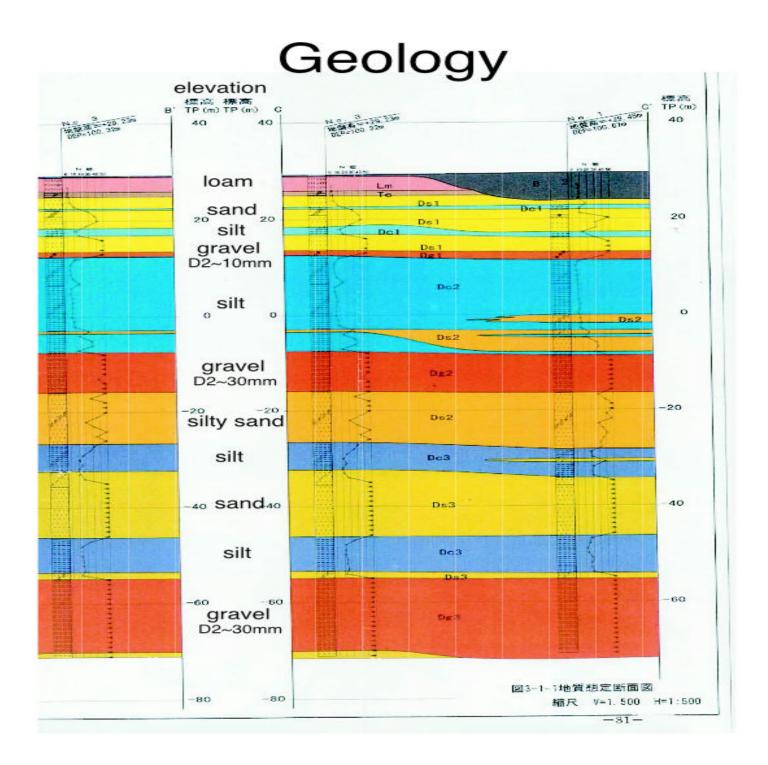
## Ground Motion Measurement at KEK





#### N.Uchida, ISG9 M.Uchida, ISG9 M.Uchida, ISG9 M.Uchida, ISG9



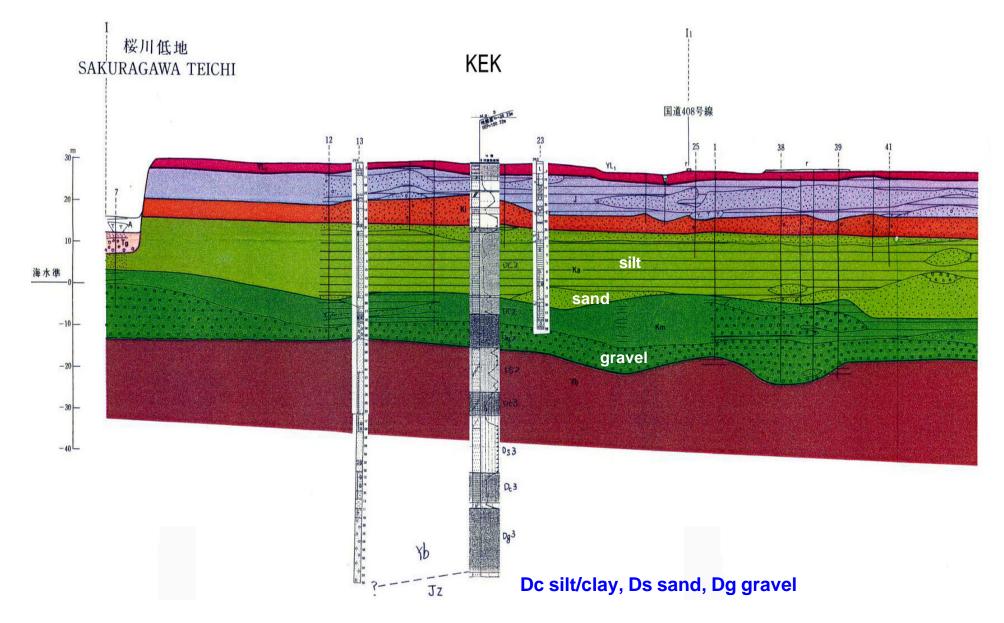


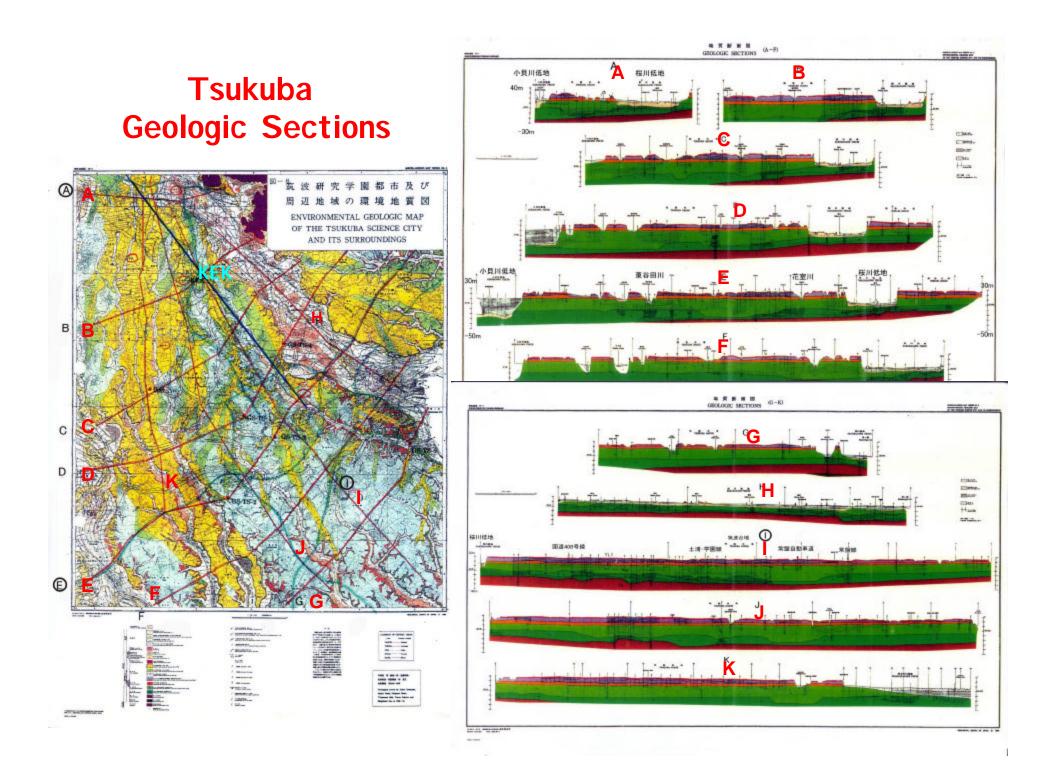
### Ground Structure Model at KEK (Oyo Co.ltd.)

depth	layer thickness	S-wave velocity	density	damping coefficient	geology
m	m	m/sec	g/cm <sup>3</sup>	%	
3	3	110	1.4	5.0	loam
4	1	110	1.6	5.0	cohesive soil(volcanic ash )
7	3	190	1.7	5.0	sand
11	4	220	1.7	5.0	silty sand
13	2	220	1.6	5.0	sandy silt
16	3	290	1.7	5.0	sandy soil
17	1	290	1.9	5.0	gravel
22	5	200	1.8	5.0	sandy silt
30	8	230	1.8	5.0	sandy silt
37	7	280	1.8	5.0	silt
45	8	600	2.0	1.3	gravel
50	5	460	1.9	1.6	silty sand
56	6	330	1.9	2.3	silty sand
63	7	310	1.8	2.4	sandy silt
75	12	390	1.9	1.9	sand with silt
84	9	270	1.8	2.8	silt, silty sand
90	6	460	2.0	1.6	gravel
99	9	750	2.0	1.0	gravel
320*	221	750	1.9	1.0	gravel

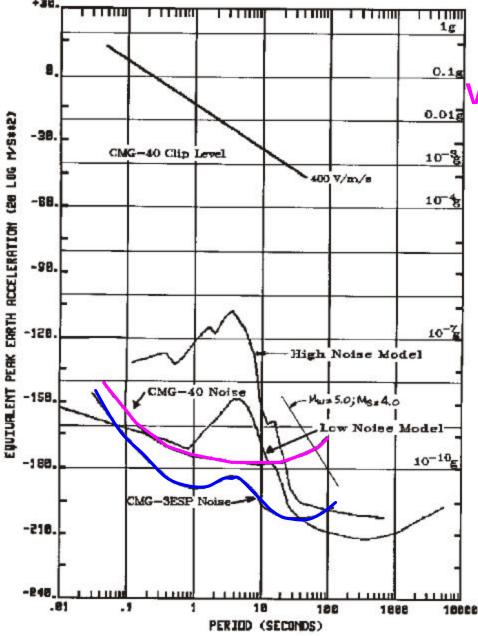
#### 図-11 JLC ルートに沿った KEK 付近のボーリング柱状図と地質断面図

### Boring result and geologic data (I)





### "30 sec" sensor : CMG40T of GURALP



Velocity Output: 2 x 400 V/m/s for borehole 2 x 800 V/m/s Frequency band: 0.033 to 50Hz

> CMG3T (100 sec sensor) Velocity Output: 2 x 750 V/m/s Flat velocity: 0.01 to 50 Hz

### Huddle Test

2003.3.10

#### CMG40T(borehole) Ch.7,8,9

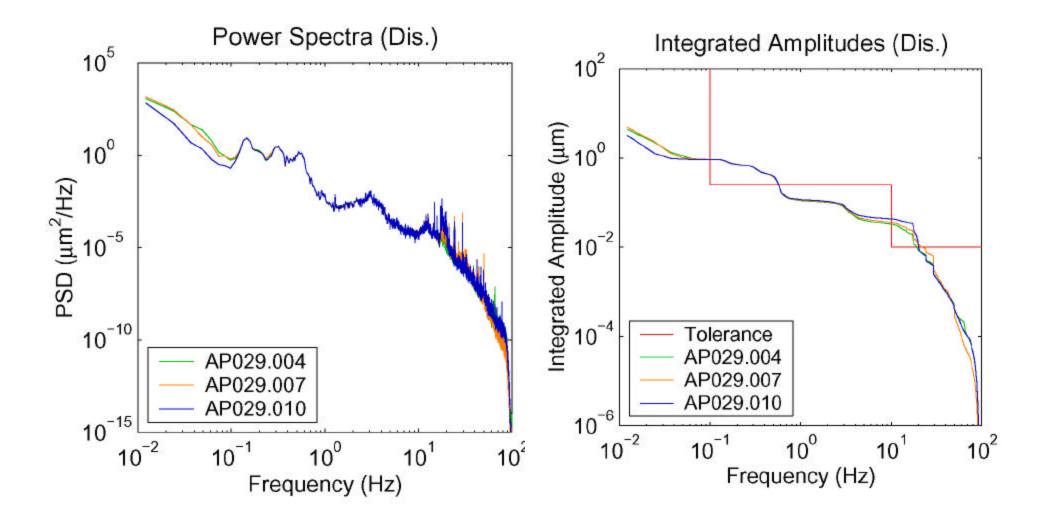
QuickTimeý Dz TIFFÅià• èkǻǵÅj êLí£ÉvÉçÉOÉâÉÄ Ç™Ç±ÇÃÉsÉNÉ`ÉÉǾå©ÇÈǾÇ'...ÇÕïKóvÇ-Ç• ÅB

CMG3T as reference Ch.10,11,12

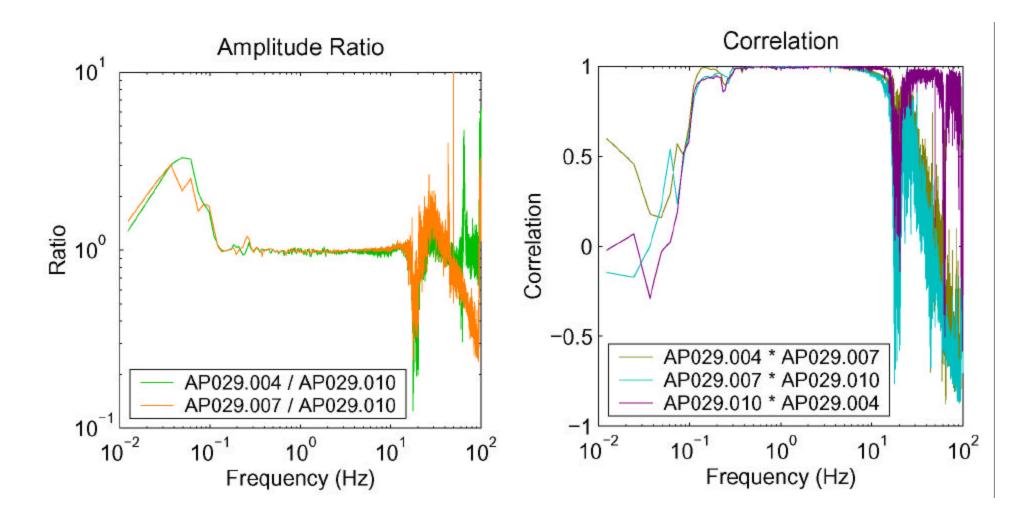
CMG40T Ch.4,5,6

### Results (1)

Gain constants are provided by GURALP.

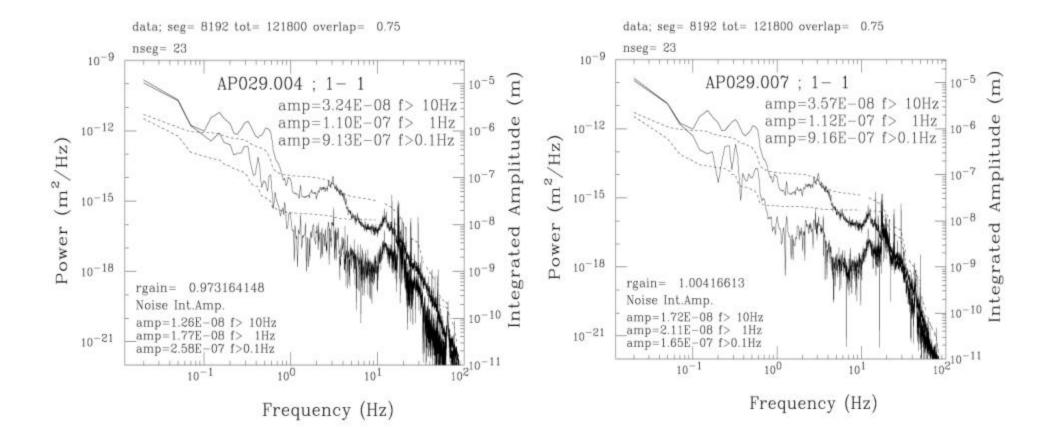


### Results (2)



### Results (3)

### "noise" estimation by PSD(1-C(PSDxPSD')<sup>1/2</sup>), PSD'=ch10 , which is true for perfect gain constants, PSD=signal +noise.

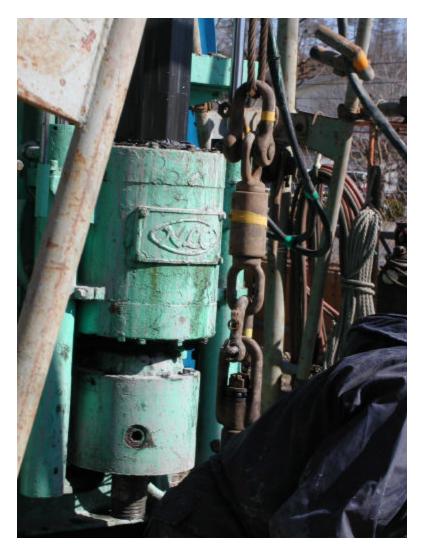


## Boring Process(1)

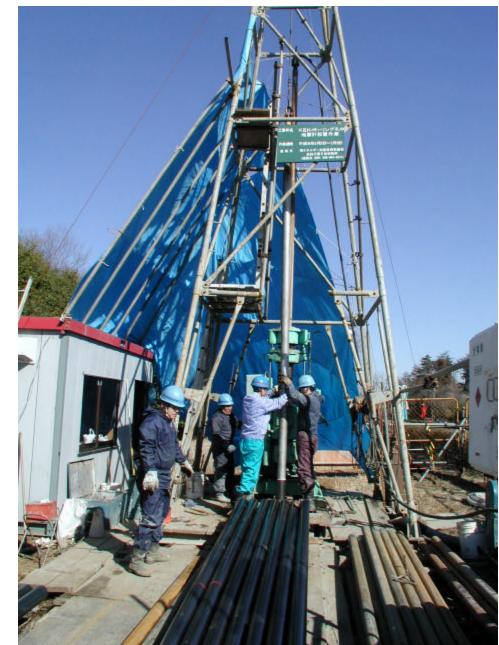




## Boring Process(2)



### Boring machine NLC



## Boring Process(3)





I nstalling glass beads to anchore the sensor.

## Setting CMG40T at GL



The sensor is surrounded by sand, and thermal insulators fill the manhole ( about 1m deep).

## GM Measurement

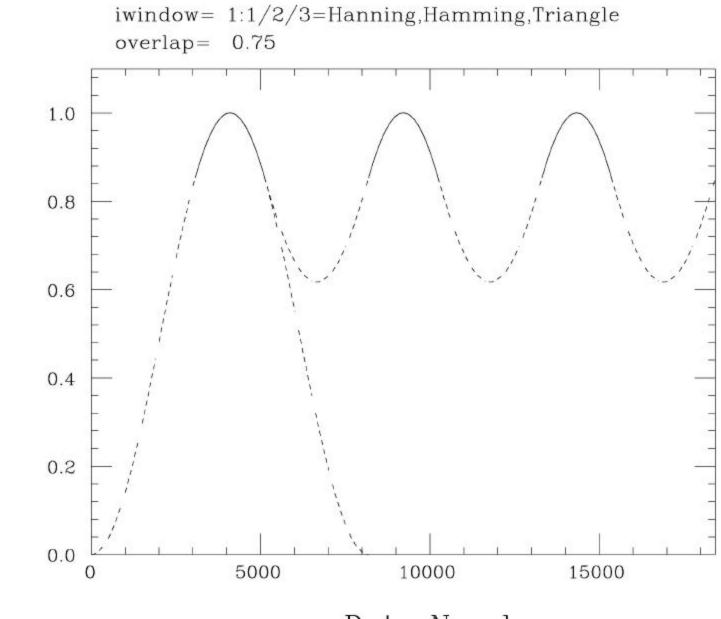
Measurement began at 10pm on 17th April, 2003. Until 29 May, 4 times per day at 4am, 10am, 4pm, 10pm. Data are taken for 30 minutes each at 200 Hz.

After 29 May, data are taken continuously at 200Hz.

The data are segmented into 40.96 sec (8192 data points) for FFT analysis with 75% overlap and <u>Hanning window</u> <u>function</u>. So, there are 69 segments for 30 minutes.

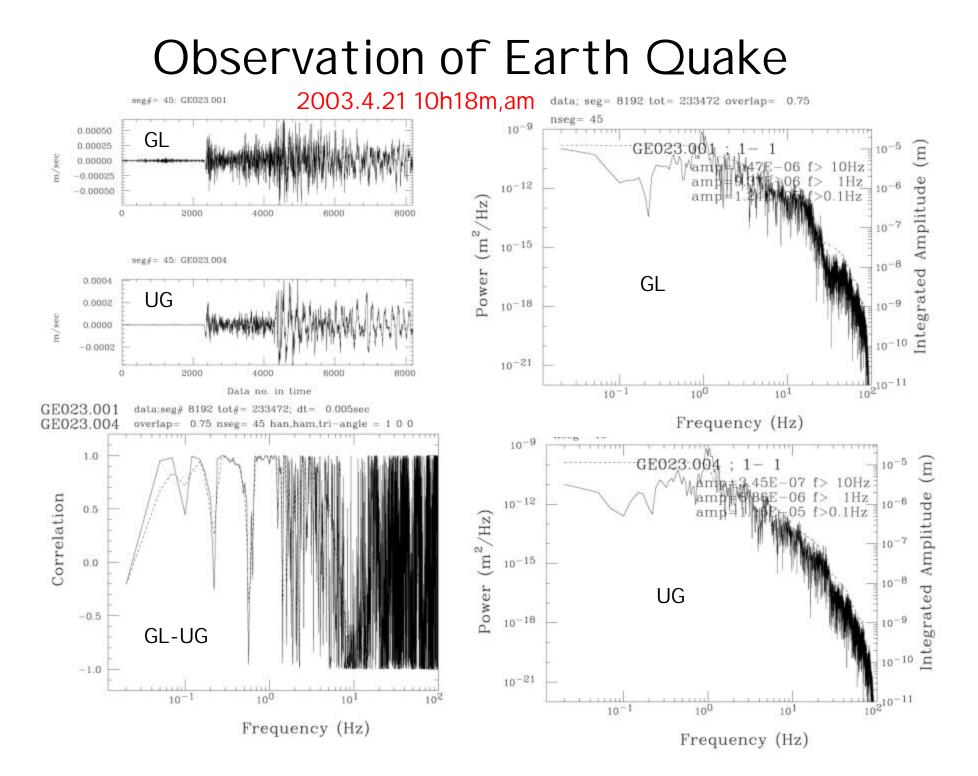
Power spectra, coherences and correlations are averages of the segments.

### Hanning Window Function

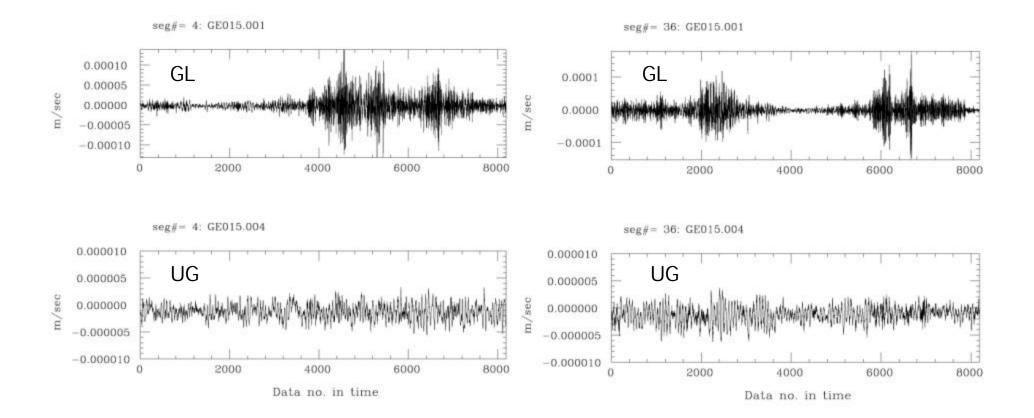


Window Function

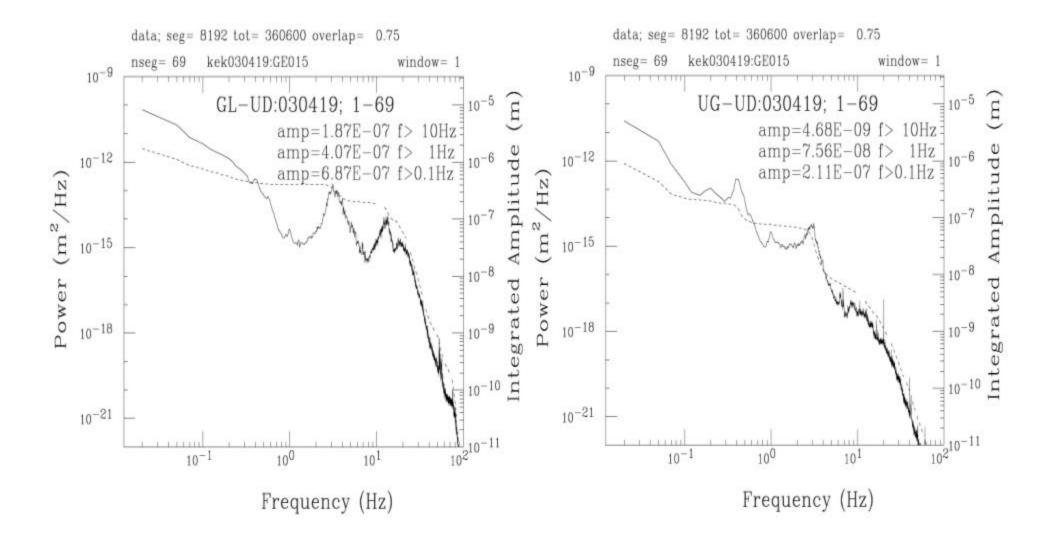
Data Number



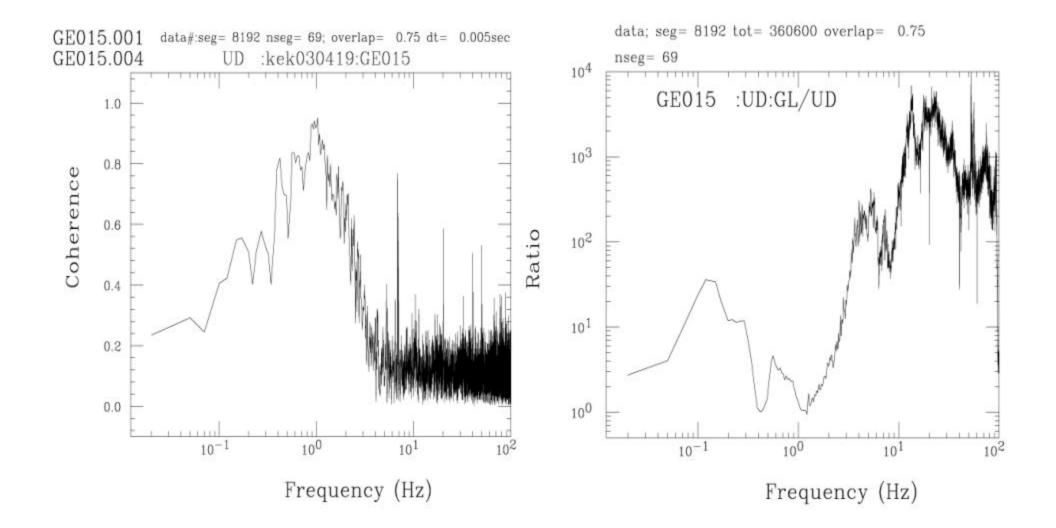
### 2003.4.19, 10am (1)

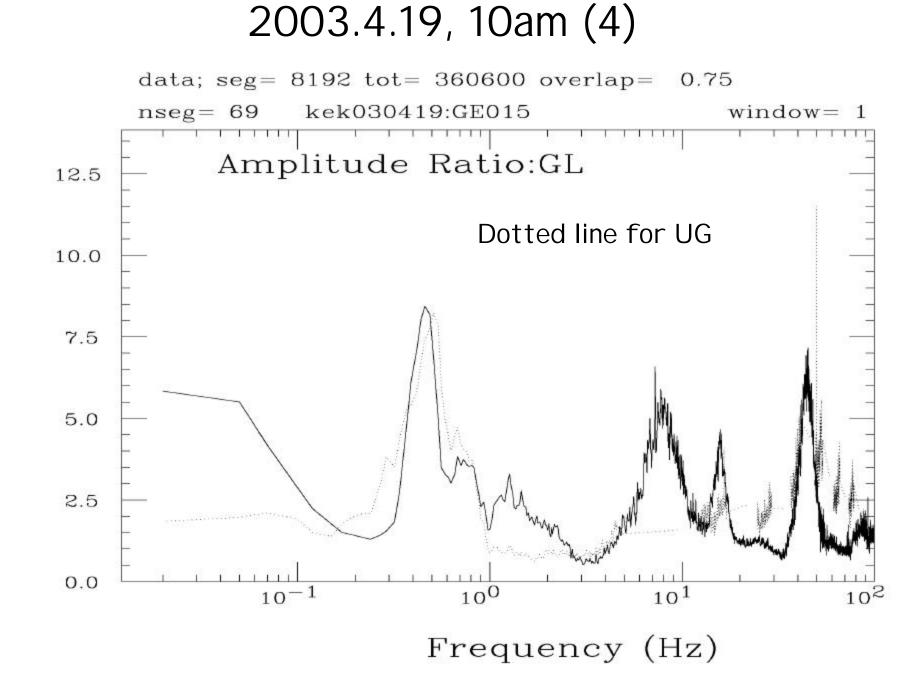


### 2003.4.19, 10am (2)



### 2003.4.19, 10am (3)

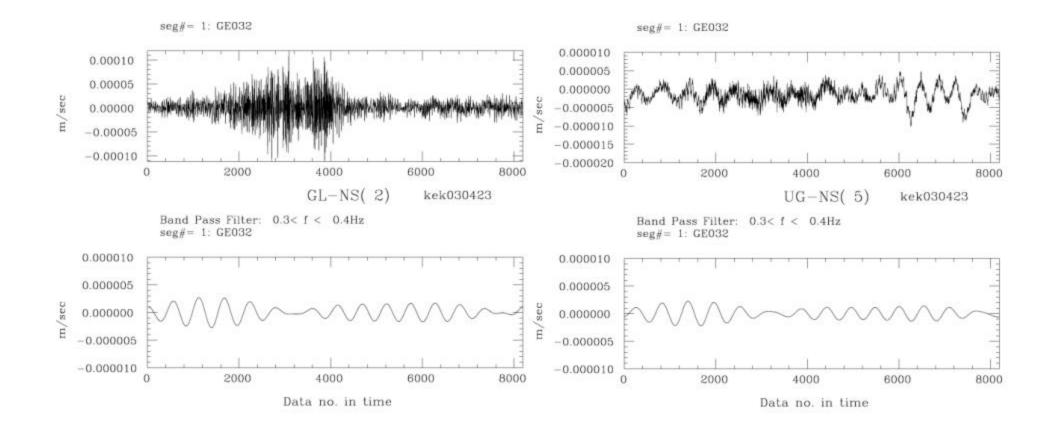




HV Ratio

## Peak at 0.3~0.4 Hz (1)

#### 2003.4.23, 4pm



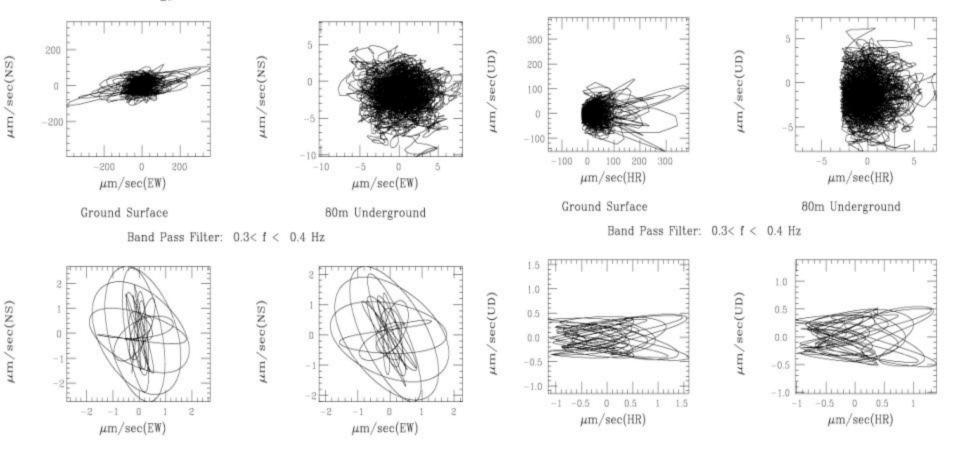
## Peak at 0.3~0.4 Hz (1)

NS - EW

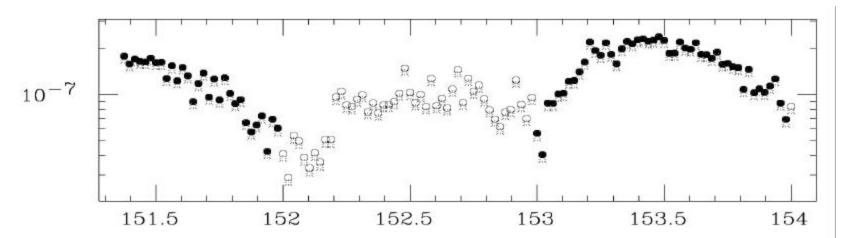
seg#= 1 1: kek030423:GE032



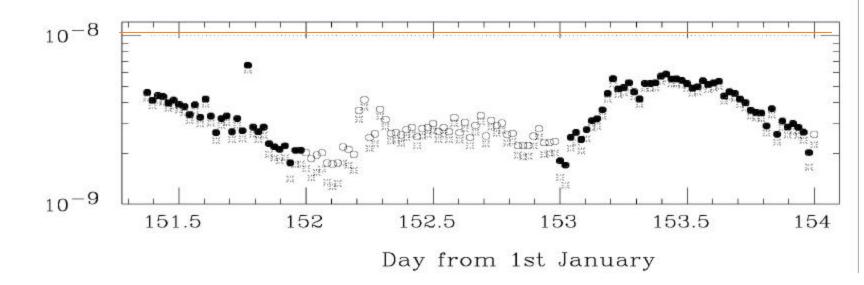
seg#= 1 1: kek030423:GE032



### UD: Integrated Amplitude at f>10Hz Daily variation; 31May(sat.)~2June(mon.)



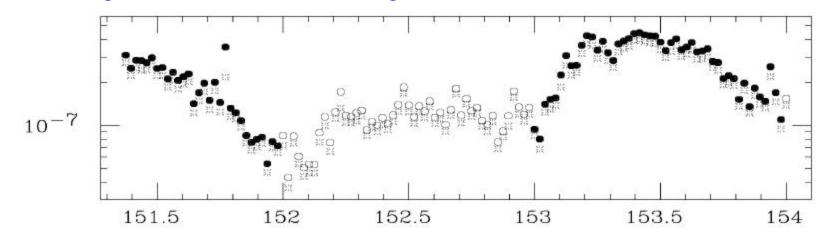
UG-UD : 10.0Hz

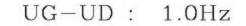


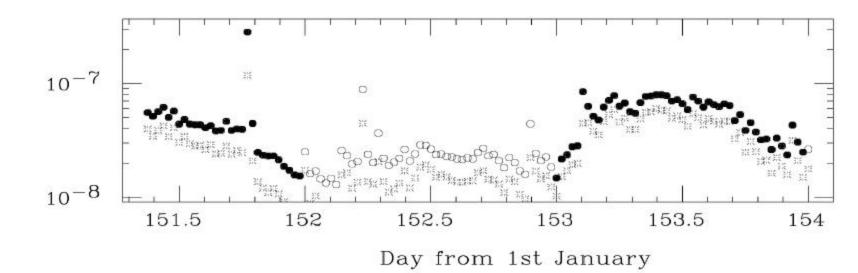
Ξ

Ξ

### UD: I ntegrated Amplitude at f>1Hz Daily variation; 31May(sat.)~2June(mon.)



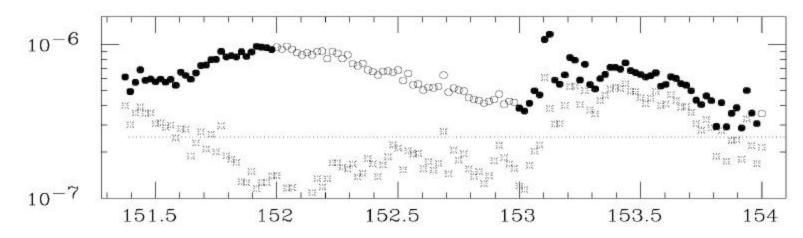




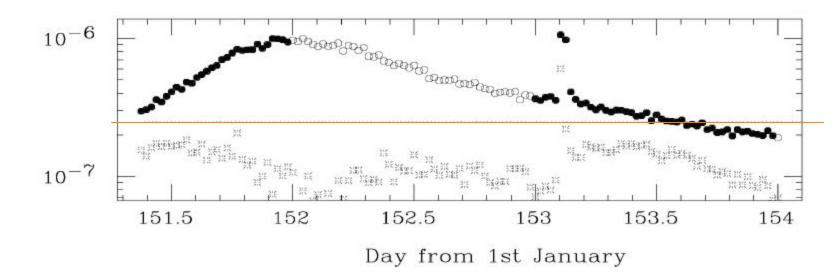
Ξ

Ξ

### UD: I ntegrated Amplitude at f>0.1Hz Daily variation; 31May(sat.)~2June(mon.)



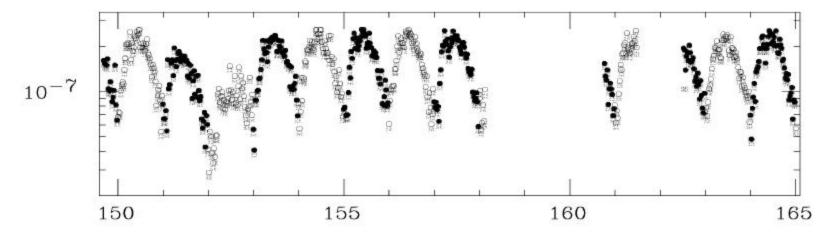
UG-UD : 0.1Hz



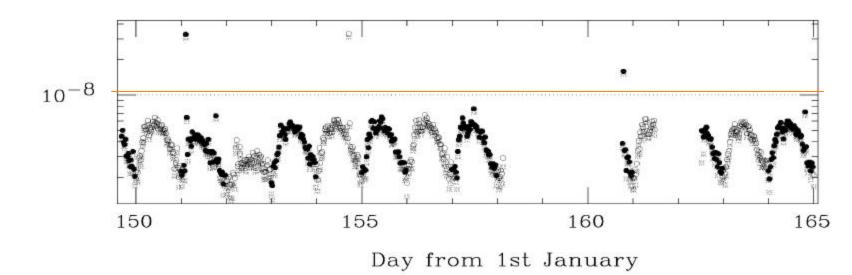
Ξ

E

### UD: Integrated Amplitude at f>10Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm

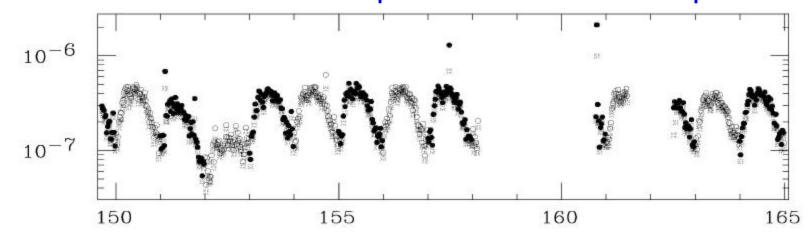


UG-UD : 10.0Hz

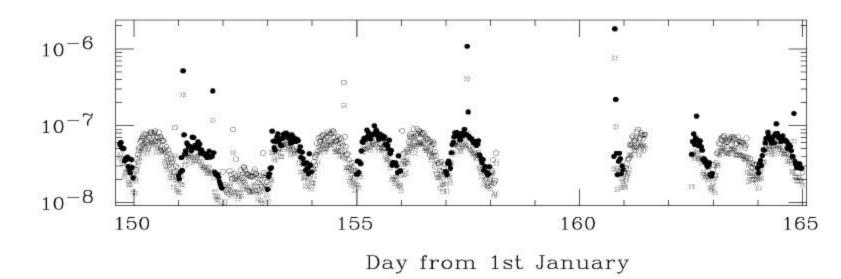


E

### UD: I ntegrated Amplitude at f>1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm



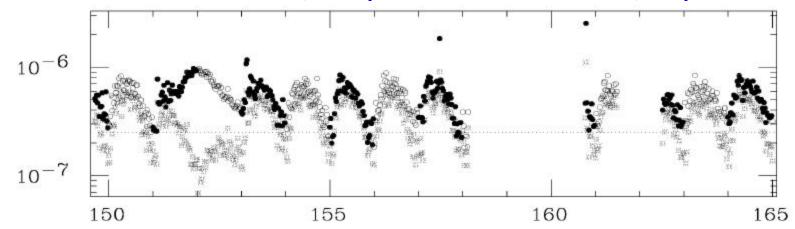
UG-UD : 1.0Hz



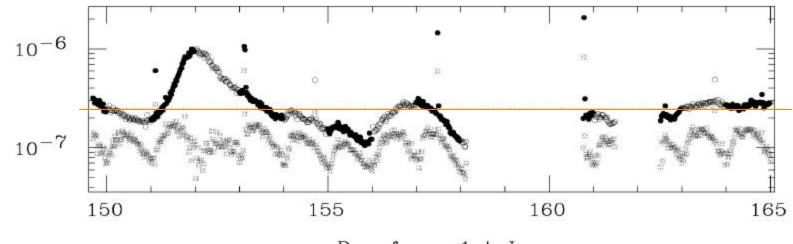
H

E

### UD: I ntegrated Amplitude at f>0.1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm



UG-UD : 0.1Hz

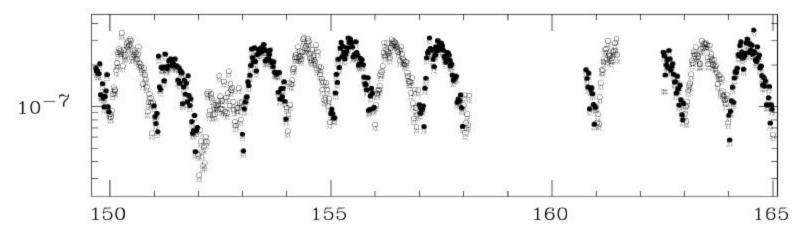


Day from 1st January

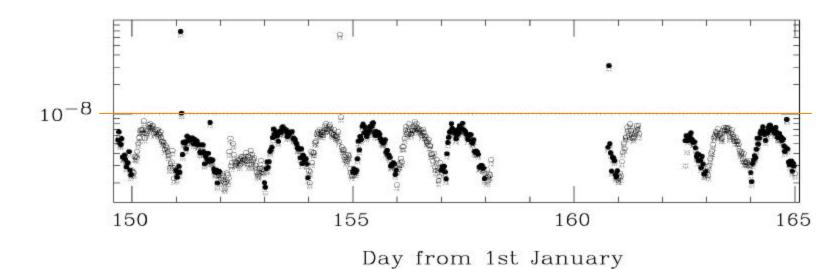
Ξ

Ξ

### NS: Integrated Amplitude at f>10Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm

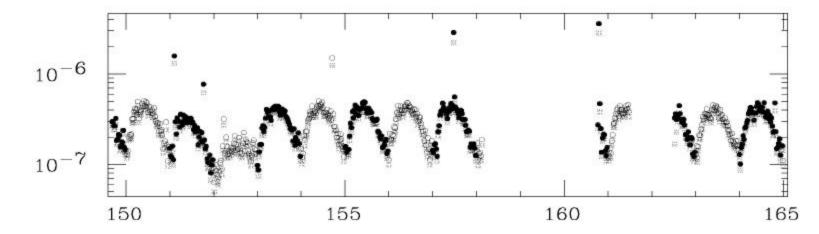


UG-NS : 10.0Hz

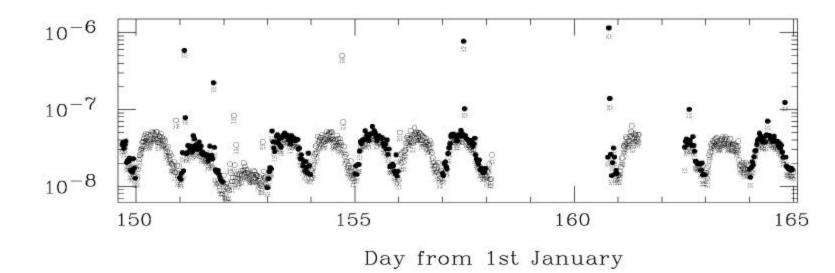


Ε

### NS:Integrated Amplitude at f>1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm

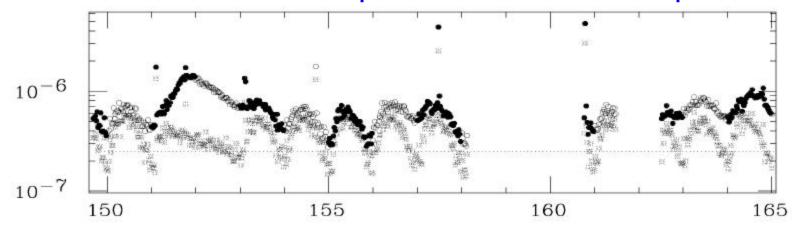


UG-NS : 1.0Hz

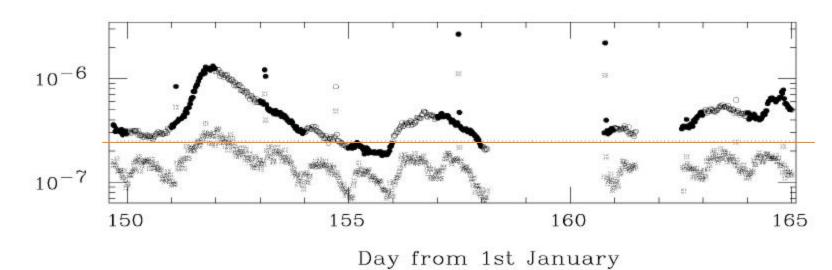


H

### NS: Integrated Amplitude at f>0.1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm

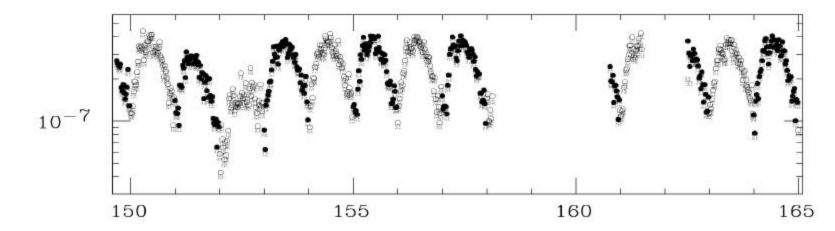


UG-NS : 0.1Hz

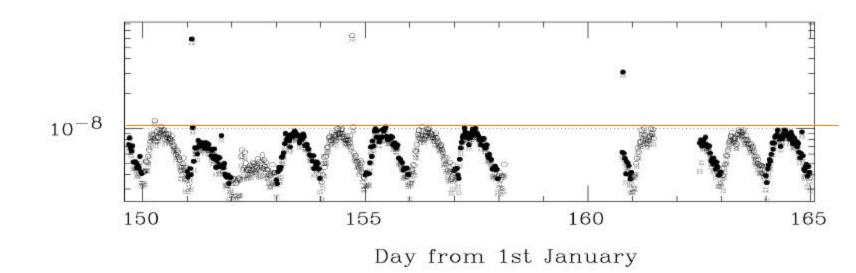


Ε

### EW: Integrated Amplitude at f>10Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm



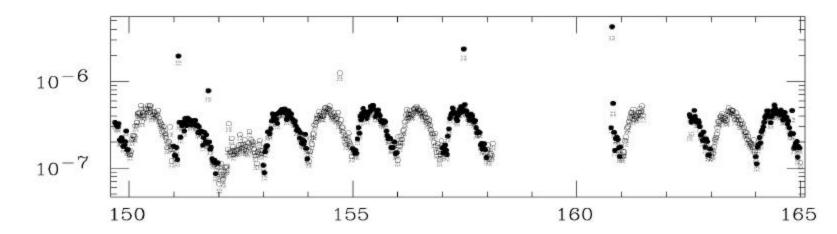
UG-EW : 10.0Hz



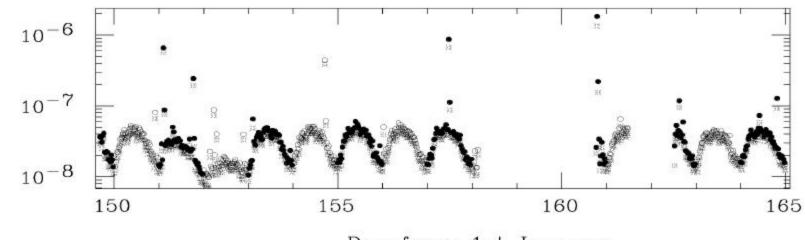
H

Н

### EW: Integrated Amplitude at f>1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm



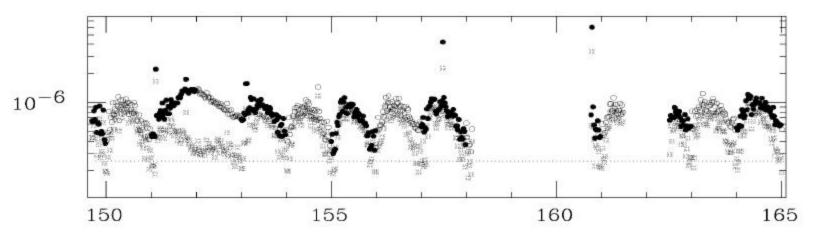
UG-EW : 1.0Hz



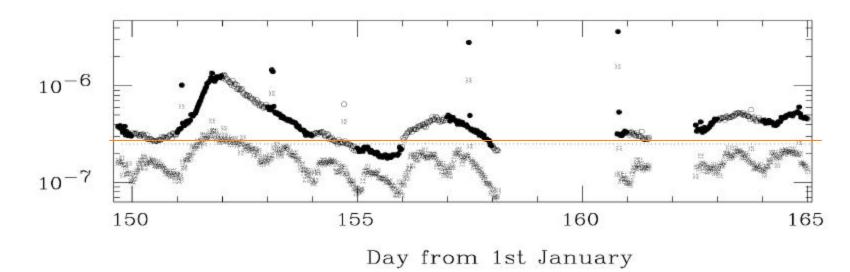
Day from 1st January

Ε

### EW: Integrated Amplitude at f>0.1Hz for 2003.5.29,4.5pm ~ 2003.6.13,12pm

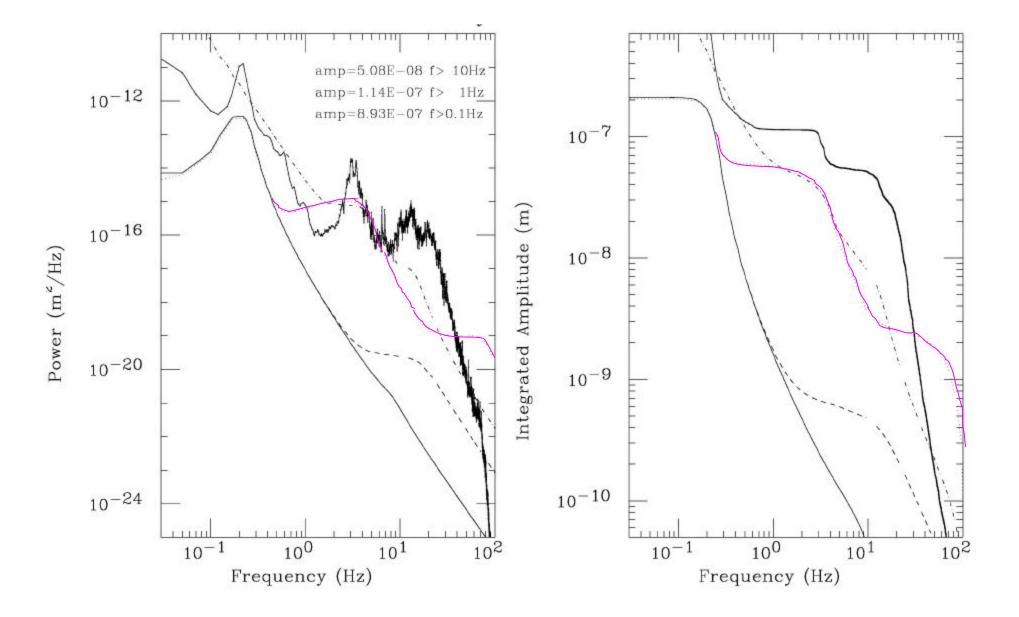


UG-EW : 0.1Hz

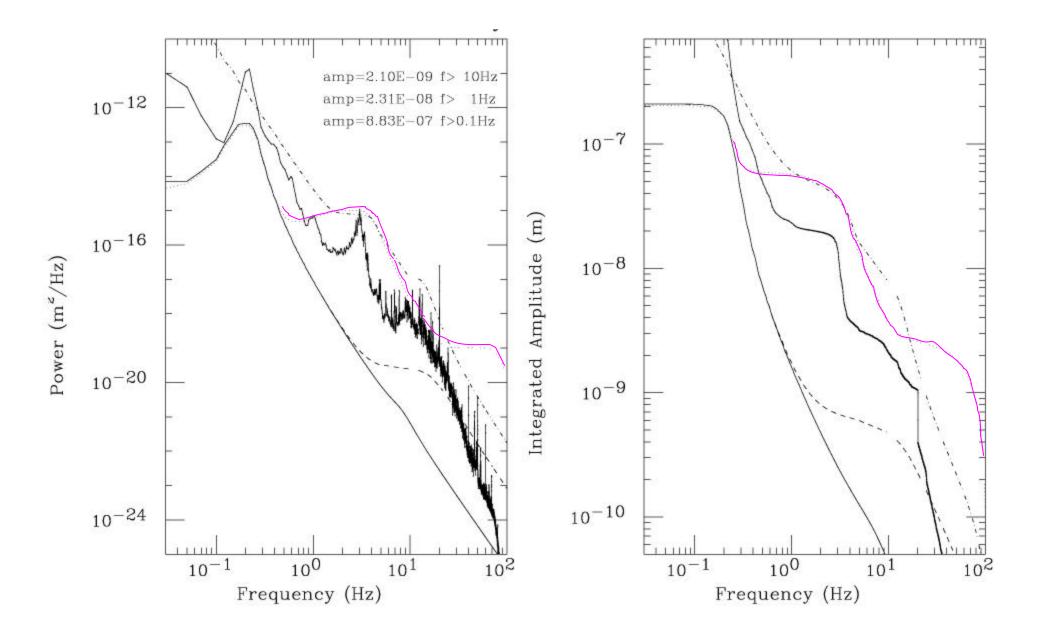


Ξ

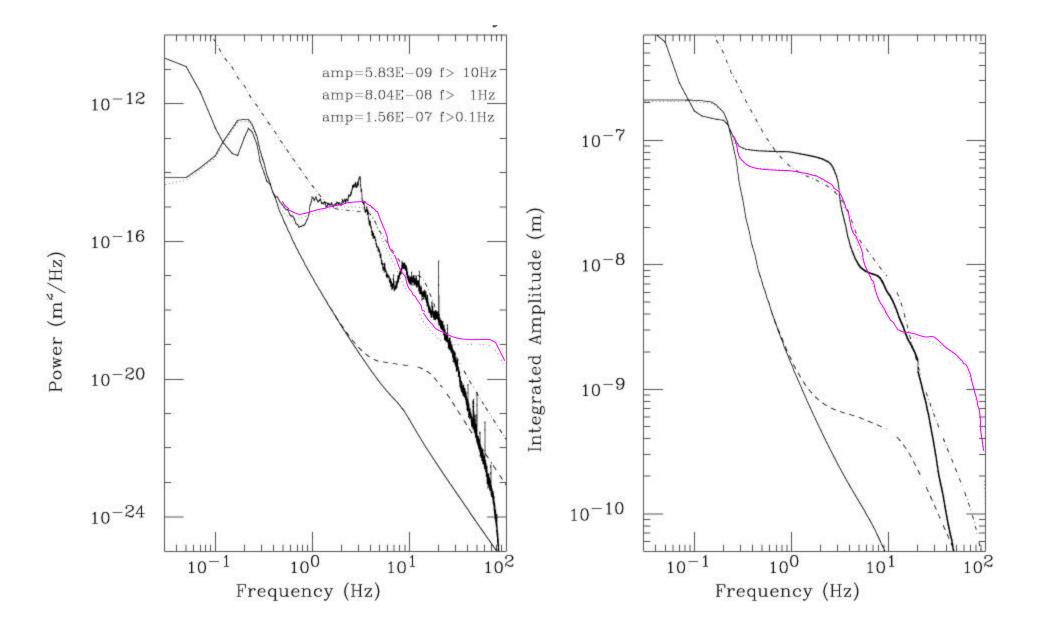
### GM-GL(2003.6.1,4am) with Models of A,B,C -36m

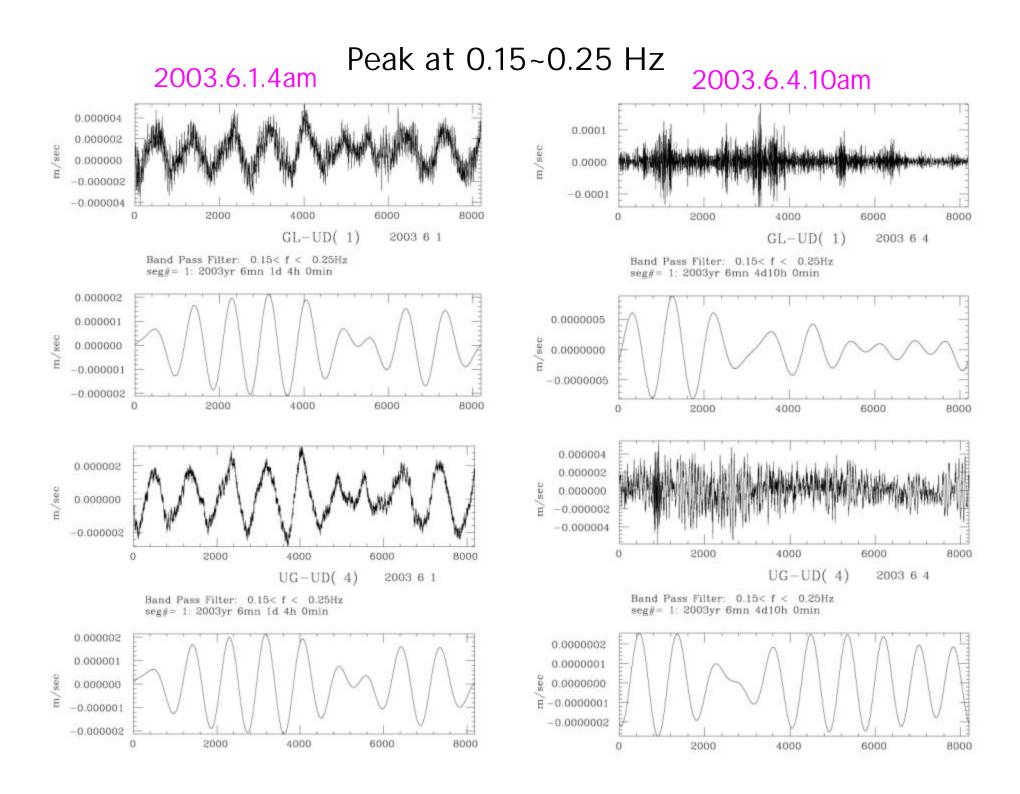


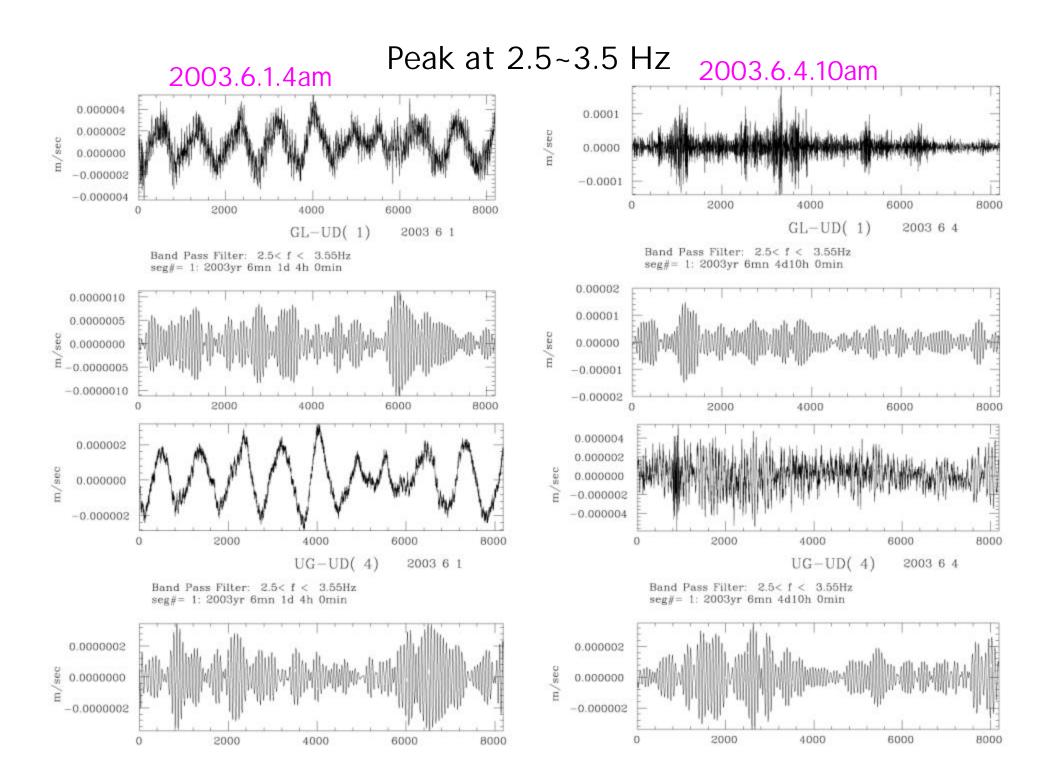
### GM-UG(2003.6.1,4am) with Models of A,B,C -36m



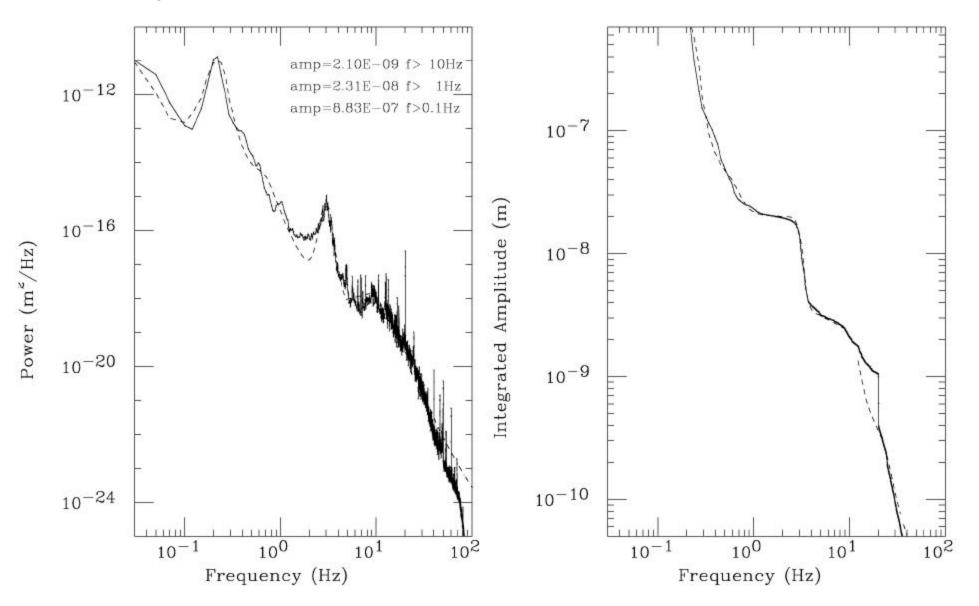
### GM-UG(2003.6.4,10am) with Models of A,B,C -36m



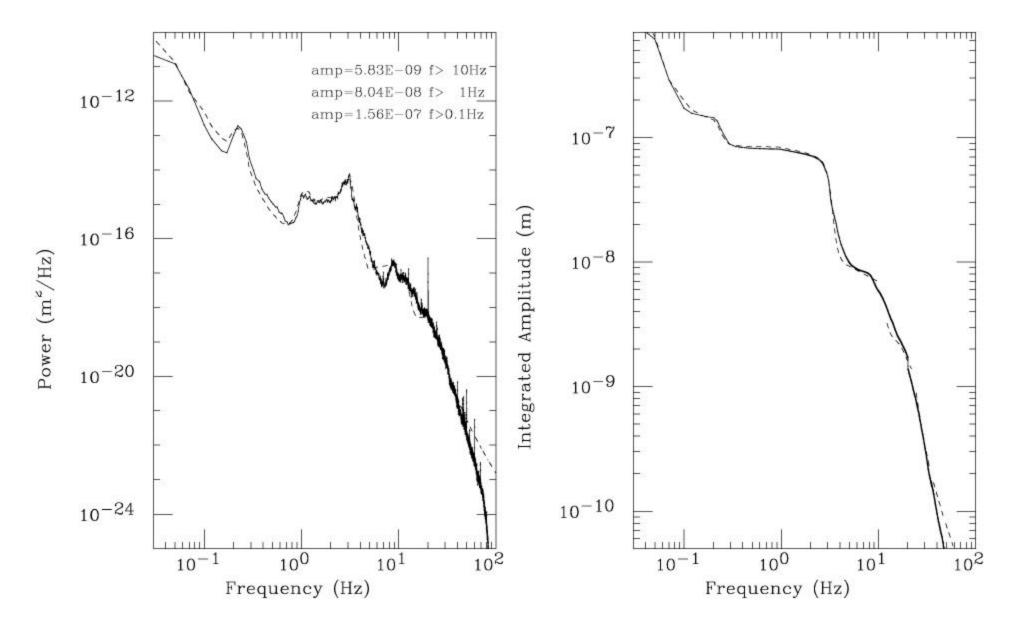




### KEK-GM Model (2003.6.1,4am) 6 "peaks" at 0.012,0.22,0.5,3.0,10.0,20.0 Hz



### KEK-GM Model (2003.6.4,10am) 7 "peaks at 0.012,0.22,1.1,2.0,3.0,10.0,20.0 Hz"



# Summary

Ground motion will be measured 80m underground as well as the surface at KEK, very near to R408(Higashi-Odori), at 200Hz for a year.

Daily and "weekly" variations were observed at higher and lower frequency regions, respectively.

GM-tolerances at 10Hz and 0.1Hz were satisfied, although daily variations were observed underground at f>0.3Hz.

GM models are made for quiet and noisy times at KEK.

The KEK GM models shall be implemented in SLEPT calculations for detailed study on the stabilization.